

*Timing*



ALGE-TIMING

Terminal

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## 1 Implementing and Keypad

Please use Timy manual GENERAL

### 1.1 *Menu*

Several standard menu-adjustments are described in the general manual for Timy. The special functions of Timy Terminal will be described in this manual.

## 2 Program Terminal

The program Terminal was developed in order to create an ideal input device for judges. The program Terminal is downward compatible to program Terminal-Computer of Comet. The new instruction set of Timy is however much more comprehensive and is described on the following sides.

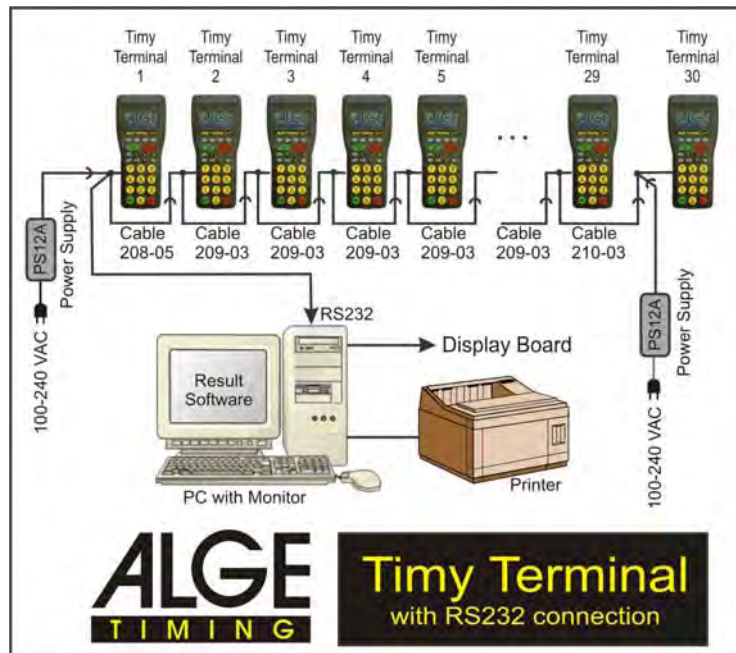
Depending on PC-Software, the user interface and operation of the Timy can be very different during the usage. Please get information of the producer of the software for the operation during an event.

### 2.1 *General*

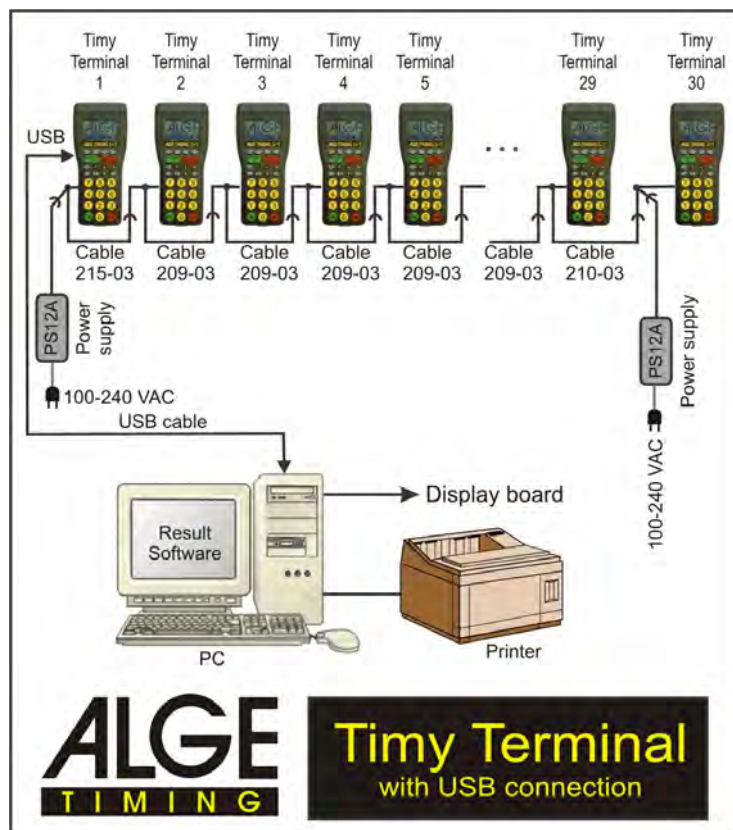
In one stream are at most 35 TIMYS possible.

There is always 1 MASTER-TIMY and up to 34 SLAVE-TIMYS.

## 2.2 Timy Terminal RS232



## 2.3 Timy Terminal USB



## 2.4 Operation of program Terminal:

After switching-on the Timy, every Timy is basically SLAVE.  
The display shows "SHALL I BE THE MASTER ? OK=YES"

Now you have to define which Timy is MASTER and which are the SLAVES.  
You can define this in two ways, first the type is described, so that you can configure all TIMYS manually.

You can adjust the number of the Timy with „MENU“->“TERMINAL“->“ADDRESS”.  
You can also indicate, how many SLAVES will be available in the stream with  
„MENU“->“TERMINAL“->“ANZ. SLAVES“

If this value is unequal zero, then this TIMY will be defined as MASTER. If this value is equal to zero, then this TIMY is defined as SLAVE.

For example: Data-stream with 5 TIMYS:

```
MASTER-TIMY:    ->ADRESS = 01
                  ->ANZ. SLAVES = 04

SLAVE:          ->ADRESS = 02
                  ->ANZ. SLAVES = 0

SLAVE:          ->ADRESS = 03
                  ->ANZ. SLAVES = 0

SLAVE:          ->ADRESS = 04
                  ->ANZ. SLAVES = 0

SLAVE:          ->ADRESS = 05
                  ->ANZ. SLAVES = 0
```

You can also configure the data-stream on another way:  
Therefore you have to adjust all TIMYS as follows:

```
->ADRESSE = 0
->ANZ. SLAVES = 0
```

Now you can define the MASTER by pressing the OK-button at one TIMY.  
Normally is every TIMY, which is connected to a PC, the MASTER.

You can also define MASTER, if the PC sends the command „TERLIST<cr>“ to the MASTER-TIMY.

Thereupon the MASTER-TIMY will start with the numbering.  
(TERLIST, TER=TERMINAL, LIST=GET LIST)

If the MASTER-TIMY retrieved all SLAVES, the numbering starts. You must one time manually assign to every SLAVE one number. The MASTER sends to all TIMYS e.b. "ARE YOU NUMBER 04 ?" You have to press the OK-button at the Timy which is spoken to.  
Go on like that until all TIMYS (including MASTER) are numbered.

**Reconnection (= next implementing) :**

If the data-stream was correctly configured once, the MASTER-TIMY will start automatically with the buildup of the data-stream and can receive commands of the PC immediately.

## 2.5 RS232 communication with PC

The MASTER-TIMY is the link between PC and the other TIMYS. There are 2 instruction sets, one of the is backward compatible to the COMET-protocol, so that even existing PC-programs can work with the TIMY data-stream. The TIMY replaces the COMET.

The new instruction set is more comprehensive but easier to use. If more than 10 TIMYS are on the data-stream, it will automatically switch to the instruction set.

### Old instruction set:

See instruction set for COMET data-stream  
Response of data-stream: „A 123456<cr>“ data of TIMY 1  
After the „A“ will be 2 blanks.

### New instruction set:

Response of data-stream „01 123456<cr>“ data of TIMY 1  
After the „01“ will be 2 blanks.

All commands begin with „TER“, enclosed is the 2-digit address of the TIMYS which will be spoken to. „FF“ responds to all TIMYS.

### The real command:

e.g. „TERFFER<cr>“ reset all TIMYS  
e.g. „TER04ER<cr>“ reset TIMY 04 (simplification compared to the old instruction set).  
e.g. „TERLIST<cr>“ sole exception: With this command you can get the data of the data-stream of the MASTER

If the data-stream is not configured yet, you can also give commands to the MASTER-TIMY, which will build the data-stream. Afterwards the MASTER-TIMY will send the information to the PC.

### Example:

The MASTER-TIMY has always the index „0“. In the square bracket is the index (internal numbering), afterwards stands the outward visible number, following 1, if the TIMY is still in the stream, otherwise 0 if he was removed. At the end you can find the 12-digits hardware-serial number

```
TERMINAL[00]=01=1=000000003449  
TERMINAL[01]=02=1=00000009a848  
TERMINAL[02]=03=1=00000005e330  
TERMINAL[03]=04=1=0000000990f6  
TERMINAL[04]=05=1=0000000993db  
TERMINAL[05]=06=1=000000099fcd  
TERMINAL[06]=07=1=000000098990  
TERMINAL[07]=08=1=00000008e399
```

# Timy terminal



Commands from the pc to the Master-Timy

Version V 1.4

from V 0971

**Important: When the pc has sent a command to the Timy, the pc has to wait for the exactly response of the sent command of the Timy before it sends the next command.**

**Despite the Master-Timy may have sent some Datas in the meanwhile, the pc has still wait for the response of the same command, which was sent before.**

These commands are from an older pc-program. Addresses from 1 to 10

M	R	C	<cr>	Clear
M	A	C	<cr>	

M	R	S	<cr>	Stop
M	C	S	<cr>	

M	R	I	<2 blanks>	Hello Infotext<cr>	Info
M	D	I	<2 blanks>	wrong Input<cr>	

M	R	T	1	A	<max. 16 characters><cr>	Text
M	E	T	2	I	<max. 16 characters><cr>	

M	R	E	R	<cr>	Reset
M	B	E	R	<cr>	

M	R	E	I	3	<cr>	Init
M	C	E	I	3	<cr>	

M	R	E	C	3	<cr>	Clear
M	C	E	C	3	<cr>	

M	R	E	S	1	" 111 22 22 22<cr>"	Set
M	C	E	S	2	" 111 22 22 22<cr>"	Set

M	R	B	<cr>	Beep for 0,1 s
M	A	B	<cr>	Beep for 0,1s to Timy A

The blue commands are from a new pc-program. Addresses from 1 to 99  
By using this syntax it is possible to control up to 99 SLAVES.

TER is the new command

Address is FF for all Timys or an 2 digit address

TER	FF	C	<cr>	Clear	blocks are set to zero
TER	01	C	<cr>		messages from the pc are cleared
					data insertion is possible
TER	FF	S	<cr>	Stop	
TER	03	S	<cr>		data insertion locked, no sending to pc allowed
TER	FF	I	<2 blanks>	Hallo Infotext<cr>	Info. In the uppermost line is the info-text.
TER	04	I	<2 blanks>	falsche Eingabe<cr>	In the lowest line is "GO ON WITH **"
TER	FF	T1A	<max. 16 Zeichen><cr>	Text to line (COMET: 1 or 2)	
TER	05	T2I	<max. 16 Zeichen><cr>		(TIMY: 1 to 8 depends to the font)

TER	FF	ER	<cr>	RESET	alle Blöcke und Texte löschen
TER	02	ER	<cr>		
TER	FF	EI	3 <cr>	INIT	Blocks to 0. BLANK and 0 means all blocks
TER	03	EI	3 <cr>		Blocks to 0. 1 to 5 means block 1 to 5
TER	FF	EC	3 <cr>	CLEAR	blocks to BLANK, the rest is like INIT
TER	03	EC	3 <cr>		blocks to BLANK, the rest is like INIT
TER	FF	ES	1 " 111 22 22 22<cr>"	SET	Line 1 or 2
TER	03	ES	2 " 111 22 22 22<cr>"		

TER	FF	F		choose the FONT													
TER	FF	F	"OEM6_8<cr>"	6 Pixel width small letters allowed max 8 lines possible	8 Pixel height <b>All characters not same width</b>												
TER	FF	F	"TIMES13<cr>"	8 Pixel width small letters allowed max 4 lines possible	13 Pixel height <b>All characters not same width</b>												
TER	FF	F	"TI8_10<cr>"	8 Pixel width No small letters max 6 lines possible	10 Pixel height <b>All characters not same width</b>												
TER	FF	F	"OEM8_16<cr>"	8 Pixel width small letters allowed max 4 lines possible	16 Pixel height <b>All characters same width</b>												
TER	FF		FLUGSCHANZE557<cr>	a special input mask will be defined like this:													
				<table border="1"> <tr> <td>Fl</td> <td>La</td> <td>Ou</td> <td></td> </tr> <tr> <td>0,0</td> <td>0,0</td> <td>0,0</td> <td>20,0</td> </tr> <tr> <td colspan="2">BIB</td> <td colspan="2">Send=OK</td> </tr> </table>	Fl	La	Ou		0,0	0,0	0,0	20,0	BIB		Send=OK		Fl=Flight, La=Landing, Ou=Out max. 5,0 5,0 7,0 20,0 max points BIB 3 digits possible after the komma only 0 or 5 allowed
Fl	La	Ou															
0,0	0,0	0,0	20,0														
BIB		Send=OK															

**TERLIST<cr>** With this command the pc starts the Timy to build up the data chain.  
 Also a list will be sent ti the pc.  
 It can look like:

**TERMINAL[00]=01=1=00000005f74e**      TERMINAL[00] is always the MASTER.  
**TERMINAL[01]=02=1=00000008e978**  
**TERMINAL[02]=03=1=00000009e300**  
**TERMINAL[03]=04=1=00000009963f**  
**TERMINAL[04]=05=1=00000005f968**      each line is terminated with <cr>  
**TERMINAL[05]=06=1=00000008ef81**  
**TERMINAL[06]=07=1=00000008eefe**  
**TERMINAL[07]=08=1=00000005eb89**

**TERMINAL[internal number]=NUMBER=present=Hardware-ID**

<b>internal number</b>	The internal number is without interest for the user.
<b>NUMBER</b>	This number can be entered in the menu on the Timy.
<b>present</b>	1 = present, 0 = absent
<b>Hardware-ID</b>	12-digits also visible in the info-menu



# Timy terminal



<b>TER WRITE-NUM:&lt;2-digit NUMBER&gt;&lt;cr&gt;</b>	You can configure a Timy as a SLAVE and give it a NUMBER.
<b>TER FF B &lt;cr&gt;</b>	<b>Beep for 0,1 s</b>
<b>TER 1 B &lt;cr&gt;</b>	<b>Beep for 0,1 s to Timy 1</b>
<b>TER FF X1 &lt;cr&gt;</b>	<b>Message "Transmitting.." appears after the OK-button was pressed.</b>
<b>TER FF X0 X0 &lt;cr&gt;</b>	<b>default: After OK-button was pressed, the screen remains unchanged After an Timy-Update this feature is set to "X0".</b>
<b>DENUM&lt;cr&gt;</b>	With this command the data chain will be completely rebuilt NOT yet defined

With the new command set the data chain can consist of up to 99 Timys.  
With the old command set the data chain can consist of up to 10 Timys.

With the new command set datas from eg. Timy 02 can be received.  
If you want to control Timy 02 you can do it with TER02<command><cr>.

With the old command set it was much more complicate and depended from the length of the data chain.

Answer from the data chain, when datas are sent.

TERMINAL	3	C 123456	03 123456	syntax of the new format
	4	<D>	04 123456	
	17	<Q>	17 123456	<b>only 1 to 9 with the</b>
	32	<'>	32 123456	<b>old format senceful</b>
	99	<special charactor of the ASCII set>		
	any	<"A" - 1 + any>		

If a SLAVE of the running chain is missed, the this message is sent from the master to the pc:

**TIMY<2 blanks><2digits NUMBER of the missed SLAVE><missing><cr>**

**Eg. "TIMY 04 missing<cr>"**

If the missed SLAVE is reconnected or a further SLAVE is added, then the MASTER sends this message to the pc:

**TIMY<2 blanks><2digits NUMBER of the missed SLAVE><present><cr>**

**Eg. "TIMY 04 present<cr>"**

## 2.5.1 Interface data

RS 232 Interface  
Standard 9600 Baud  
8 Data Bit, no Parity Bit, 1 Stop Bit  
ASCII signs

## 2.5.2 RS 232 instruction set

Look at pages 10 and 11.

Command set: Timy	V2.9	19.11.2009	green=already built in	Backup	PC-Timer	Stopwatch	Tracktimer	Training Light	Training Ref	Laptimer	Cyclostart	Commander	Speed	Windspeed	Terminal	Qualtimer
<b>meaning</b>	<b>syntax</b>	<b>parameter</b>	<b>example</b>	<b>syntax description</b>												
enter bib	#	4 digits	#1234	enters a bib over serial port or usb												
enter bib	#	1234-<bl>/>	#1234b #1234i	bib for blueleft parcour												
enter bib	#	1234-<bl>/>	#1234f	bib for redright parcour												
enter bib	#	1234C<0 or 1>	#1234C0 #1234C1	bib for start (C0) or finish (C1)												
only for gsm-modem	*	Only the gsm-modem can send this to the Timy, and then some further commands are following														
automatic time min	AZN	HH:MM:SS	AZN12:00:00 AZN?	request, set												
automatic time max	AZX	HH:MM:SS	AZX12:00:00 AZX?	request, set												
beep	BE	0 or 1	BEO BETBE?	request, on off												
User-Prog-Update	BWF		USB-TIMY-BWF!!!	than update-file												
Classement memoryline	CALMT		CALMT	Classement memoryline												
Classement runtime	CALRT		CALRT	Classement runtime												
Classement totalline	CALTT		CALTT	Classement totalline												
Cyclometer signal 1	C1		C1	request, on off												
Cyclometer signal 2	C2		C2	request, on off												
Cyclometer signal 3	C3		C3	request, on off												
Cyclometer signal 4	C4		C4	request, on off												
Cyclometer signal 5	C5		C5	request, on off												
Cyclometer signal 6	C6		C6	request, on off												
Cyclometer signal 7	C7		C7	request, on off												
Cyclometer signal 8	C8		C8	request, on off												
Cyclometer signal 9	C9		C9	request, on off												
Cyclometer signal 10	C10		C10	request, on off												
Cyclometer signal 11	C11		C11	request, on off												
Cyclometer signal 12	C12		C12	request, on off												
Cyclometer signal 13	C13		C13	request, on off												
Cyclometer signal 14	C14		C14	request, on off												
Cyclometer signal 15	C15		C15	request, on off												
Cyclometer signal 16	C16		C16	request, on off												
Cyclometer signal 17	C17		C17	request, on off												
Cyclometer signal 18	C18		C18	request, on off												
Cyclometer signal 19	C19		C19	request, on off												
Cyclometer signal 20	C20		C20	request, on off												
Cyclometer signal 21	C21		C21	request, on off												
Cyclometer signal 22	C22		C22	request, on off												
Cyclometer signal 23	C23		C23	request, on off												
Cyclometer signal 24	C24		C24	request, on off												
Cyclometer signal 25	C25		C25	request, on off												
Cyclometer signal 26	C26		C26	request, on off												
Cyclometer signal 27	C27		C27	request, on off												
Cyclometer signal 28	C28		C28	request, on off												
Cyclometer signal 29	C29		C29	request, on off												
Cyclometer signal 30	C30		C30	request, on off												
Cyclometer signal 31	C31		C31	request, on off												
Cyclometer signal 32	C32		C32	request, on off												
Cyclometer signal 33	C33		C33	request, on off												
Cyclometer signal 34	C34		C34	request, on off												
Cyclometer signal 35	C35		C35	request, on off												
Cyclometer signal 36	C36		C36	request, on off												
Cyclometer signal 37	C37		C37	request, on off												
Cyclometer signal 38	C38		C38	request, on off												
Cyclometer signal 39	C39		C39	request, on off												
Cyclometer signal 40	C40		C40	request, on off												
Cyclometer signal 41	C41		C41	request, on off												
Cyclometer signal 42	C42		C42	request, on off												
Cyclometer signal 43	C43		C43	request, on off												
Cyclometer signal 44	C44		C44	request, on off												
Cyclometer signal 45	C45		C45	request, on off												
Cyclometer signal 46	C46		C46	request, on off												
Cyclometer signal 47	C47		C47	request, on off												
Cyclometer signal 48	C48		C48	request, on off												
Cyclometer signal 49	C49		C49	request, on off												
Cyclometer signal 50	C50		C50	request, on off												
Cyclometer signal 51	C51		C51	request, on off												
Cyclometer signal 52	C52		C52	request, on off												
Cyclometer signal 53	C53		C53	request, on off												
Cyclometer signal 54	C54		C54	request, on off												
Cyclometer signal 55	C55		C55	request, on off												
Cyclometer signal 56	C56		C56	request, on off												
Cyclometer signal 57	C57		C57	request, on off												
Cyclometer signal 58	C58		C58	request, on off												
Cyclometer signal 59	C59		C59	request, on off												
Cyclometer signal 60	C60		C60	request, on off												
Cyclometer signal 61	C61		C61	request, on off												
Cyclometer signal 62	C62		C62	request, on off												
Cyclometer signal 63	C63		C63	request, on off												
Cyclometer signal 64	C64		C64	request, on off												
Cyclometer signal 65	C65		C65	request, on off												
Cyclometer signal 66	C66		C66	request, on off												
Cyclometer signal 67	C67		C67	request, on off												
Cyclometer signal 68	C68		C68	request, on off												
Cyclometer signal 69	C69		C69	request, on off												
Cyclometer signal 70	C70		C70	request, on off												
Cyclometer signal 71	C71		C71	request, on off												
Cyclometer signal 72	C72		C72	request, on off												
Cyclometer signal 73	C73		C73	request, on off												
Cyclometer signal 74	C74		C74	request, on off												
Cyclometer signal 75	C75		C75	request, on off												
Cyclometer signal 76	C76		C76	request, on off												
Cyclometer signal 77	C77		C77	request, on off												
Cyclometer signal 78	C78		C78	request, on off												
Cyclometer signal 79	C79		C79	request, on off												
Cyclometer signal 80	C80		C80	request, on off												
Cyclometer signal 81	C81		C81	request, on off												
Cyclometer signal 82	C82		C82	request, on off												
Cyclometer signal 83	C83		C83	request, on off												
Cyclometer signal 84	C84		C84	request, on off												
Cyclometer signal 85	C85		C85	request, on off												
Cyclometer signal 86	C86		C86	request, on off												
Cyclometer signal 87	C87		C87	request, on off												
Cyclometer signal 88	C88		C88	request, on off												
Cyclometer signal 89	C89		C89	request, on off												
Cyclometer signal 90	C90		C90	request, on off												
Cyclometer signal 91	C91		C91	request, on off												
Cyclometer signal 92	C92		C92	request, on off												
Cyclometer signal 93	C93		C93	request, on off												
Cyclometer signal 94	C94		C94	request, on off												
Cyclometer signal 95	C95		C95	request, on off												
Cyclometer signal 96	C96		C96	request, on off												
Cyclometer signal 97	C97		C97													

# Timy terminal



Command	Description	Parameters	Response	Notes
RT	running tenth	0 or 1	RTO RTT RT7	
SAF	skin automatic for finish	0.1 or 2	SAFO SAF1 SAF2	
SAS	skin automatic for start	0.1 or 2	SASO SAS1 SAS2	
SL	START LOGO	0 or 1	SLD SL1 SL7	
SM	second mode	0 or 1	SMO SM1 SM7	
SPDI	Speed distance in meters	0000.1 to 9999.9 or 0001 to 9999 or ?	SPDI0100<cr> SPDI0100.5<cr>	
SPDR	Speed direction	0.1 or 2	SPDR0 SPDR1	
SPU	Speed Unit	0.1 or 2	SPU0 SPU1 SPU2	
SPMI	Speed minimum	0000.1 to 9999.9 or 0001 to 9999 or ?	SPMI0000.1	
SPMX	Speed maximum	0001.0 to 9999.9 or 0001 to 9999 or ?	SPMX0200.0	
SPTI	Speed Print Times	0 or 1	SPTI1 SPTI0	
SP2	Only for the communication with the OPTIC-device.			
TER	Advanced subset of data-chain		TERFER	
TIMYINIT	initialize the timy, gets HW-ID	? Or #1234 (while # = 0 to 8)	TIMYINIT	
DTC	Delaytime for a specific channel	max. 24 characters	DTC#01.78	
DTP	Direct transmission to printer		DTPHelloWorld	
CHK	enables or disables the checksum	7,0 or 1	CHK7,CHK1,CHK0	
EMU	send time every s or tenths or not	?,0.1 or 2	EMU7,EMU0,EMU2	
RSP	send memory from pos. a to b	aaaaabbbb	RSP0010000500	
RSS	send memory from STN a to b	aaaaabbbb	RSS0002000020	
RSUA	Send memory universal A	Caaaaabbbb	RSUA100108989	
RSUB	Send memory universal B	Caaaaabbbb	RSUBA000000002300000000	
SPEC	Special command		SPEC7	
	This command should be sent over usb		SPEC:STOPWATCH\$A1	
	This command should be sent over usb		SPEC:STOPWATCH\$A0	
	This command should be sent over usb		SPEC:STOPWATCH\$B0	
	This command should be sent over usb		SPEC:STOPWATCH\$B1	
	This command should be sent over usb		SPEC:STOPWATCH\$B2	
	This command should be sent over usb		SPEC:STOPWATCH\$B3	
	This command should be sent over usb		SPEC:STOPWATCH\$C0	
	This command should be sent over usb		SPEC:STOPWATCH\$C1	
	This command should be sent over usb		SPEC:STOPWATCH\$C2	
	This command should be sent over usb		SPEC:STOPWATCH\$C3	
	This command should be sent over usb		SPEC:STOPWATCH\$A1<cr>	
SYNA	synchronize the Timy	hh:mm:ss:zhz	SYNA12.00.00.0000	
SYNM		hh:mm:ss:zhz	SYNM00.30.00.0000	
SYND		YY:MM:DD	SYND04-10-31	
SST	Send start time	NNNN CO hh:mm:ss:zhz RR	SST 1234 CO 12:34:56 7890 NN=Startnumber, hh=hour,mm=minutes,ss=seconds, zhz=4 digits of second's fraction, RR =always 00	
DTP	Direct transmission to printer	max. 100 characters	DTPHelloWorld	
HELP	Show the list of the commands		HELP	
9600 baud	standard baudrate			
ASCII	Syntax for command and parameter			
Hardware-Handshake	not built in, later possible (RTS/CTS)			
Software-Handshake	not built in, later possible (XON/XOFF)			
command not supported	send back NOT			
command understood	send back the command without parameter			
command with ?	send back the command with parameter			
command not understood	send back nothing			
command with unvalid parameters	send back nothing			
safe communication				
If the pc has sent a command to the Timy, the pc has to wait for the acknowledge, before sending the next command				
Acknowledge means that the sent command must be returned from the Timy.				
Each command can be sent by rs232 or USB.				
For programming the usb-interface, use only the Alge-OOX-File.				
Note: If you see <cr> at an example, please be aware that this is only one character not 4 characters.				

